**ENGR 4020 Lab 7 [25 pts]**

**Robotics System Toolbox**

**Submit by 3/27/2020**

**Tasks**

1. Complete the example on path planning at <https://www.mathworks.com/help/robotics/examples/path-planning-in-environments-of-difference-complexity.html>
2. Complete the example on path planning of a differential drive robot at <https://www.mathworks.com/help/robotics/examples/plan-path-for-a-differential-drive-robot-in-simulink.html>
3. Submit documentation of completion of each of these examples
4. The remaining lab time is free to use on work toward your next milestone